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Khin Soe Nwe

In recognition of the publication of the paper entitled
**Dynamic Modeling and Simulation of Articulated Robotic Arm with MATLAB Robotics System
Toolbox**

Published in Volume 3 Issue 11, November-2018, | Impact Factor: 9.15 by Google Scholar

Co-Authors - Wai Phyo Maung, Ei Ei Htwe

Paper ID - IJSDR1811012
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